SSE 2300/CE 4990: Systems Design and Engineering

Review of Probability Theory

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Definitions

- Probability: A description of the likelihood of events expression of uncertainty.
- Experiment: A process whose outcome is subject to uncertainty.
- Sample space: A set of possible outcomes. $S = \{1, 2, 3, 4, 5, 6\}$
- Sample point: A single outcome in the S. $x = \{3\}$
- **Event:** A subset of *S*. $E = \{1, 2, 3\}$
- $E_1, E_2, ..., E_n$ is a partition of the sample space S, if they are **mutually exclusive and** collectively exhaustive.
- Set operations: Union (\cup) , Intersection (\cap) , Complement ('), Mutually exclusive or disjoint sets, Empty set (ϕ) , Collectively exhaustive.

Axioms of Probability

P(.) is a function that maps subsets of S into [0, 1]. The fundamental axioms are:

- For every event A, $P(A) \ge 0$.
- For the same le space S, P(S) = 1
- If $\{A_i | i = 1, ..., n\}$ is a finite collection of mutually exclusive events then $P(A_1 \cup A_2 \cup ... \cup A_n) = \sum P(A_i)$

Properties that follow:

- $P(A) \leq 1$
- $\forall A, P(A) = 1 P(A')$
- $P(\phi) = 0$
- For mutually exclusive events A and B, $P(A \cap B) = 0$
- For any two events, A and B, $P(A \cup B) = P(A) + P(B) P(A \cap B)$

Conditional Probability and Bayes Theorem

P(A|B) = Probability of A given that B has occurred. $P(A|B) = P(A \cap B)/P(B)$. Therefore $P(A \cap B) = P(A|B) * P(B)$.

Bayes Theorem

Let $E_1, E_2, ..., E_n$ be a partition of the sample space S with $P(E_i) > 0$ for i = 1, ..., n, then for any event A for which P(A) > 0:

$$P(E_k|A) = \frac{P(A|E_k).P(E_k)}{\sum_{i=1}^{n} P(A|E_i)P(E_i)}$$

Mathematical Independence

When the knowledge of event A has no impact on the probability of the event B then they are said to be mathematically independent and this relationship is expressed as:

A and $B \in S$ are independent iff P(B|A) = P(B), or $P(A \cap B) = P(A).P(B)$

Law of Total Probability

Let $E_1, E_2, ..., E_n$ be a partition of the sample space S, then for any event A,

 $P(A) = \sum_{i=1}^{n} P(A|E_i)P(E_i)$